

Singular Value Decomposition

Singular Value Decomposition (SVD)

- singular value decomposition of a $M \times N$ matrix \underline{A} with rank R :

$$\underline{A} = \underbrace{(\underline{u}_1, \dots, \underline{u}_M)}_{\substack{\underline{U} \\ \text{unitary} \\ M \times M \text{ matrix}}} \cdot \underbrace{\begin{pmatrix} \sigma_1 & & 0 & & \\ & \ddots & & & \\ 0 & & \sigma_R & & \\ \hline & & & & \\ & 0 & & & 0 \end{pmatrix}}_{\substack{\underline{\Sigma} \\ \text{nonnegative} \\ M \times N \text{ diagonal} \\ \text{matrix}}} \cdot \underbrace{\begin{pmatrix} \underline{v}_1^{*T} \\ \vdots \\ \underline{v}_N^{*T} \end{pmatrix}}_{\substack{\underline{V}^{*T} \\ \text{unitary} \\ N \times N \text{ matrix}}}$$

- exists for any matrix \underline{A}
- singular values in nonincreasing order:

$$\sigma_1 \geq \dots \geq \sigma_R > \sigma_{R+1} = \dots = \sigma_{\min(M, N)} = 0$$

Remarks

- The left singular vectors $\underline{u}_1, \dots, \underline{u}_N$ are the eigenvectors of the Hermitian $N \times N$ matrix

$$\begin{aligned}\underline{A} \cdot \underline{A}^{*T} &= \underline{U} \cdot \underline{\Sigma} \cdot \underline{V}^{*T} \cdot \underline{V} \cdot \underline{\Sigma}^{*T} \cdot \underline{U}^{*T} \\ &= \underline{U} \cdot (\underline{\Sigma} \cdot \underline{\Sigma}^T) \cdot \underline{U}^{*T}.\end{aligned}$$

- The right singular vectors $\underline{v}_1, \dots, \underline{v}_N$ are the eigenvectors of the Hermitian $N \times N$ matrix

$$\begin{aligned}\underline{A}^{*T} \cdot \underline{A} &= \underline{V} \cdot \underline{\Sigma}^{*T} \cdot \underline{U}^{*T} \cdot \underline{U} \cdot \underline{\Sigma} \cdot \underline{V}^{*T} \\ &= \underline{V} \cdot (\underline{\Sigma}^T \cdot \underline{\Sigma}) \cdot \underline{V}^{*T}.\end{aligned}$$

- The nonzero singular values $\sigma_1, \dots, \sigma_R$ are the square roots of the positive eigenvalues of $\underline{A} \cdot \underline{A}^{*T}$ or $\underline{A}^{*T} \cdot \underline{A}$.

Four Subspaces

- The left singular vectors u_1, \dots, u_r corresponding to the nonzero singular values span the column space of dimension R .
- The remaining left singular vectors u_{r+1}, \dots, u_n span the left nullspace of dimension $n-r$.
- The right singular vectors v_1, \dots, v_r corresponding to the nonzero singular values span the row space of dimension R .
- The remaining right singular vectors v_{r+1}, \dots, v_n span the nullspace of dimension $n-r$.

Frobenius Norm

- norm of a matrix:

$$\|\underline{A}\|_F = \sqrt{\sum_m \sum_n |[A]_{m,n}|^2}$$

$$= \sqrt{\text{trace}(\underline{A} \cdot \underline{A}^{*T})}$$

$$= \sqrt{\text{trace}(\underline{A}^{*T} \cdot \underline{A})}$$

$$= \sqrt{\sum_r \sigma_r^2}$$

- squares of the singular values of \underline{A}
- eigenvalues of $\underline{A} \cdot \underline{A}^{*T}$
- eigenvalues of $\underline{A}^{*T} \underline{A}$

- multiplication with a unitary matrix \underline{U}^{*T} or \underline{V} does not change the norm:

$$\|\underline{U}^{*T} \cdot \underline{A} \cdot \underline{V}\|_F = \|\underline{A}\|_F$$

Matrix Approximation

- Find a rank Q approximation \underline{B} of \underline{A} such that the error $\|\underline{A} - \underline{B}\|_F^2$ is minimized.
- singular value decomposition:

$$\underline{A} = \underbrace{(\underline{U}_1, \underline{U}_2)}_{\underline{U}} \cdot \underbrace{\begin{pmatrix} \Sigma_1 & 0 \\ 0 & \Sigma_2 \end{pmatrix}}_{\Sigma} \cdot \underbrace{\begin{pmatrix} \underline{V}_1^{*T} \\ \underline{V}_2^{*T} \end{pmatrix}}_{\underline{V}^{*T}}$$

\uparrow first Q columns Q largest singular values $Q \times Q$ \uparrow first Q rows

$$\begin{aligned} \Rightarrow \|\underline{A} - \underline{B}\|_F^2 &= \|\underline{U}^{*T} \cdot (\underline{A} - \underline{B}) \cdot \underline{V}\|_F^2 \\ &= \|\Sigma - \underline{U}^{*T} \cdot \underline{B} \cdot \underline{V}\|_F^2 \end{aligned}$$

- The best rank Q approximation of the diagonal matrix

$$\Sigma = \begin{pmatrix} \Sigma_1 & 0 \\ 0 & \Sigma_2 \end{pmatrix}$$

is

$$\underline{U}^{*T} \cdot \underline{B} \cdot \underline{V} = \begin{pmatrix} \Sigma_1 & 0 \\ 0 & 0 \end{pmatrix}.$$

$$\Rightarrow \underline{B} = \underbrace{(\underline{U}_1, \underline{U}_2)}_{\underline{U}} \cdot \begin{pmatrix} \Sigma_1 & 0 \\ 0 & 0 \end{pmatrix} \cdot \underbrace{\begin{pmatrix} \underline{V}_1^{*T} \\ \underline{V}_2^{*T} \end{pmatrix}}_{\underline{V}^{*T}}$$

$$= \underline{U}_1 \cdot \Sigma_1 \cdot \underline{V}_1^{*T}$$

"keep the Q largest singular values"

Least Squares (LS)

- singular value decomposition:

$$\underline{A} = \underline{U} \cdot \underbrace{\begin{pmatrix} \sigma_1 & & 0 \\ & \ddots & \\ 0 & & \sigma_r \\ & & & 0 \\ & & & & \ddots \\ & & 0 & & & 0 \end{pmatrix}}_{\Sigma, M \times N \text{ matrix}} \cdot \underline{V}^{*T}$$

- pseudoinverse of a diagonal matrix:

$$\Sigma^+ = \begin{pmatrix} 1/\sigma_1 & & 0 \\ & \ddots & \\ 0 & & 1/\sigma_r \\ & & & 0 \\ & & & & \ddots \\ & & 0 & & & 0 \end{pmatrix} \quad N \times M \text{ matrix}$$

- linear system of equations:

$$\begin{array}{ccc} \underline{A} \cdot \underline{x} = \underline{b} \\ \downarrow \quad \downarrow \quad \downarrow \\ M \times N \quad N \times 1 \quad M \times 1 \end{array}$$

has in general no exact solution

- least squares pseudosolution:

$$\hat{\underline{x}} = \underset{\underline{x}}{\operatorname{argmin}} \|\underline{A} \cdot \underline{x} - \underline{b}\|_F^2$$

$$= \underset{\underline{x}}{\operatorname{argmin}} \|\underline{U} \cdot \Sigma \cdot \underline{V}^{*T} \cdot \underline{x} - \underline{b}\|_F^2$$

$$= \underset{\underline{x}}{\operatorname{argmin}} \|\Sigma \cdot \underline{V}^{*T} \cdot \underline{x} - \underline{U}^{*T} \cdot \underline{b}\|_F^2$$

$$\Rightarrow \underline{V}^{*T} \cdot \hat{\underline{x}} = \Sigma^+ \cdot \underline{U}^{*T} \cdot \underline{b}$$

$$\hat{\underline{x}} = \underbrace{\underline{V} \cdot \Sigma^+ \cdot \underline{U}^{*T}}_{\underline{A}^+} \cdot \underline{b}$$

pseudoinverse

Left Pseudoinverse

- full rank $M \times N$ matrix \underline{A} :

$$\text{rank}(\underline{A}) = N \leq M$$

- pseudoinverse:

$$\underline{A}^+ = \underline{V} \cdot \underline{\Sigma}^+ \cdot \underline{U}^{*T}$$

$$= \underline{V} \cdot \underbrace{(\underline{\Sigma}^{*T} \cdot \underline{\Sigma})^{-1}} \cdot \underline{\Sigma}^{*T} \cdot \underline{U}^{*T}$$

$$\begin{pmatrix} \frac{1}{\sigma_1^2} & & 0 \\ & \ddots & \\ 0 & & \frac{1}{\sigma_N^2} \end{pmatrix}$$

$$= \underline{V} \cdot (\underline{\Sigma}^{*T} \cdot \underline{U}^{*T} \cdot \underline{U} \cdot \underline{\Sigma})^{-1} \cdot \underline{V}^{*T} \cdot \underline{V} \cdot \underline{\Sigma}^{*T} \cdot \underline{U}^{*T}$$

$$= \underbrace{(\underline{V} \cdot \underline{\Sigma}^{*T} \cdot \underline{U}^{*T} \cdot \underline{U} \cdot \underline{\Sigma} \cdot \underline{V}^{*T})^{-1}}_{\underline{A}^{*T}} \cdot \underbrace{\underline{V} \cdot \underline{\Sigma}^{*T} \cdot \underline{U}^{*T}}_{\underline{A}^+}$$

$$= \underbrace{(\underline{A}^{*T} \cdot \underline{A})^{-1}}_{\text{invertible}} \cdot \underline{A}^{*T}$$

- left pseudoinverse:

$$\underline{A}^+ \cdot \underline{A} = (\underline{A}^{*T} \cdot \underline{A})^{-1} \cdot \underline{A}^{*T} \cdot \underline{A} = \underline{E}$$

Right Pseudoinverse

- full rank $M \times N$ matrix \underline{A} :

$$\text{rank}(\underline{A}) = M \leq N$$

- pseudoinverse:

$$\underline{A}^+ = \underline{V} \cdot \underline{\Sigma}^+ \cdot \underline{U}^{*T}$$

$$= \underline{V} \cdot \underline{\Sigma}^{*T} \cdot \underbrace{(\underline{\Sigma} \cdot \underline{\Sigma}^{*T})^{-1}} \cdot \underline{U}^{*T}$$

$$\begin{pmatrix} \frac{1}{\sigma_1^2} & & 0 \\ & \ddots & \\ 0 & & \frac{1}{\sigma_n^2} \end{pmatrix}$$

$$= \underline{V} \cdot \underline{\Sigma}^{*T} \cdot \underline{U}^{*T} \cdot \underline{U} \cdot (\underline{\Sigma} \cdot \underline{V}^{*T} \cdot \underline{V} \cdot \underline{\Sigma}^{*T})^{-1} \cdot \underline{U}^{*T}$$

$$= \underbrace{\underline{V} \cdot \underline{\Sigma}^{*T} \cdot \underline{U}^{*T}}_{\underline{A}^{*T}} \cdot \underbrace{(\underline{U} \cdot \underline{\Sigma} \cdot \underline{V}^{*T} \cdot \underline{V} \cdot \underline{\Sigma}^{*T} \cdot \underline{U}^{*T})^{-1}}_{\underline{A}} \cdot \underbrace{\underline{U}^{*T}}_{\underline{A}^{*T}}$$

$$= \underline{A}^{*T} \cdot \underbrace{(\underline{A} \cdot \underline{A}^{*T})^{-1}}_{\text{invertible}}$$

- right pseudoinverse:

$$\underline{A} \cdot \underline{A}^+ = \underline{A} \cdot \underline{A}^{*T} \cdot (\underline{A} \cdot \underline{A}^{*T})^{-1} = \underline{E}$$

Total Least Squares (TLS)

- Find matrices $\underline{\Delta}_A$ and $\underline{\Delta}_B$ of minimum square Frobenius norm $\|(\underline{\Delta}_A, \underline{\Delta}_B)\|_F^2$ such that

$$(\underline{A} + \underline{\Delta}_A) \cdot \underline{X} = (\underline{B} + \underline{\Delta}_B) \cdot$$

- reformulation of the constraint:

$$\underbrace{(\underline{A} + \underline{\Delta}_A, \underline{B} + \underline{\Delta}_B)}_{\substack{\downarrow \\ N \times N \quad N \times L}} \cdot \underbrace{\begin{pmatrix} \underline{X} \\ -E \end{pmatrix}}_{\substack{\uparrow \\ N \times L \\ \downarrow \\ L \times L}} = \underbrace{0}_{\substack{\downarrow \\ N \times L}}$$

must have a nullspace of dimension L ←

$$\Rightarrow \text{rank}(\underline{A} + \underline{\Delta}_A, \underline{B} + \underline{\Delta}_B) = N$$

$$\Rightarrow (\underline{A} + \underline{\Delta}_A, \underline{B} + \underline{\Delta}_B) \text{ is a rank } N \text{ approximation of } (\underline{A}, \underline{B})$$

- Using the singular value decomposition

$$(\underline{A} + \underline{\Delta A}, \underline{B} + \underline{\Delta B}) = \underbrace{(\underline{U}_1, \underline{U}_2)}_{\substack{\uparrow \\ \text{first } N \text{ columns} \\ \underline{U}, N \times N}} \cdot \underbrace{\begin{pmatrix} \Sigma_1 & 0 \\ 0 & 0 \end{pmatrix}}_{\substack{\uparrow \\ N \times N \\ \Sigma, N \times N+L}} \cdot \underbrace{\begin{pmatrix} \underline{V}_1^{*T} \\ \underline{V}_2^{*T} \end{pmatrix}}_{\substack{\uparrow \\ \text{first } N \text{ rows} \\ \underline{V}, N+L \times N+L}}$$

one obtains

$$(\underline{A} + \underline{\Delta A}, \underline{B} + \underline{\Delta B}) = \underline{U}_1 \cdot \Sigma_1 \cdot \underline{V}_1^{*T}.$$

$$\Rightarrow \underbrace{\underline{U}_1}_{\substack{\downarrow \\ \text{full rank}}} \cdot \Sigma_1 \cdot \underline{V}_1^{*T} \cdot \begin{pmatrix} \underline{X} \\ -E \end{pmatrix} = 0$$

$$\underline{V}_1^{*T} \cdot \begin{pmatrix} \underline{X} \\ -E \end{pmatrix} = 0$$

$$\Rightarrow \text{The columns of } \begin{pmatrix} \underline{X} \\ -E \end{pmatrix} \text{ must be}$$

orthogonal to the columns of \underline{V}_1 ,
i.e., they must be linear
combinations of the orthogonal
complement \underline{V}_2 :

$$\begin{pmatrix} \underline{X} \\ -E \end{pmatrix} = \underline{V}_2 \cdot \underline{G}$$

- Using

$$\underline{V} = \begin{pmatrix} \underline{V}_{11} & \underline{V}_{12} \\ \underline{V}_{21} & \underline{V}_{22} \end{pmatrix}$$

$N \times N$ (top-left), $N \times L$ (top-right), $L \times N$ (bottom-left), $L \times L$ (bottom-right)

one obtains

$$\underline{V}_{22} \cdot \underline{C} = -E$$

$$\underline{C} = -\underline{V}_{22}^{-1}$$

and finally

$$\begin{aligned} \underline{X} &= \underline{V}_{12} \cdot \underline{C} \\ &= -\underline{V}_{12} \cdot \underline{V}_{22}^{-1} \end{aligned}$$

- \underline{V} can also be computed by the eigendecomposition of

$$\begin{pmatrix} \underline{A}^{*T} \\ \underline{B}^{*T} \end{pmatrix} \cdot (\underline{A}, \underline{B}) = \underline{V} \cdot \underline{\Sigma}^T \cdot \underline{\Sigma} \cdot \underline{V}^{*T}$$

(instead of the singular value decomposition of $(\underline{A}, \underline{B})$):